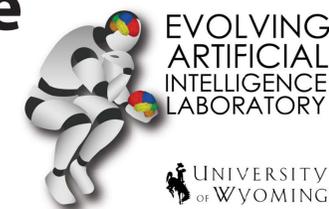


# Deep Curiosity Search: Intra-life exploration can improve performance on challenging deep reinforcement learning problems

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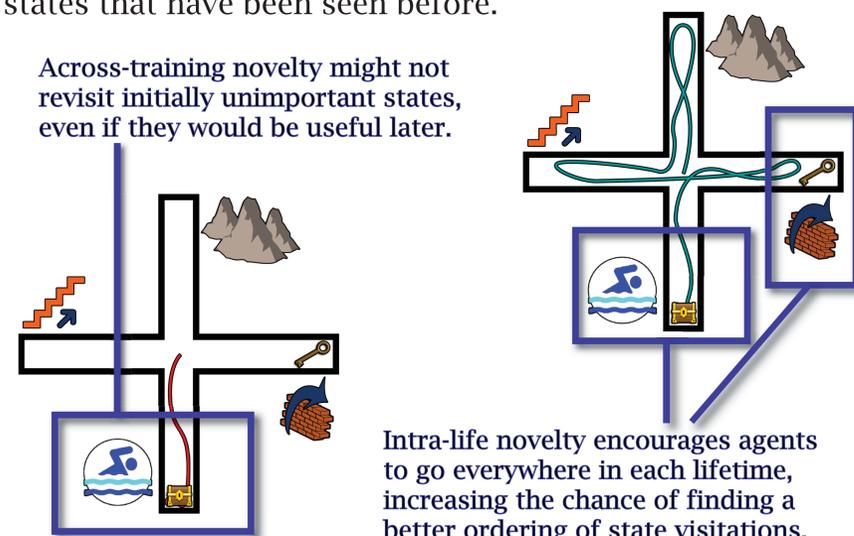
## Overview

We introduce Deep Curiosity Search (DeepCS), a directed exploration algorithm inspired by intrinsic motivation in animals, that rewards agents for “doing something new” within their lifetime. Using some domain knowledge, DeepCS matches the performance of other state-of-the-art techniques on hard Atari games like Montezuma’s Revenge.

## Background

Traditional exploration methods reward *across-training novelty*: whether a state is new compared to all other states that have been seen before.

Across-training novelty might not revisit initially unimportant states, even if they would be useful later.

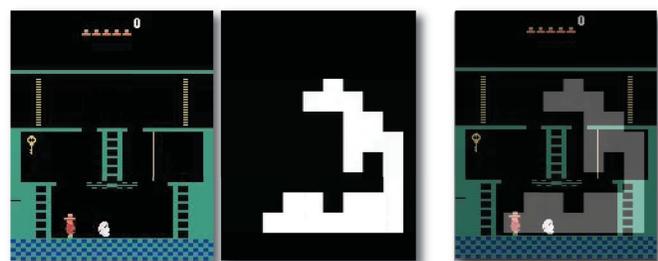


Intra-life novelty encourages agents to go everywhere in each lifetime, increasing the chance of finding a better ordering of state visitations.

Curiosity Search instead encourages *intra-life novelty*, rewarding agents for visiting new states even if they have been seen in prior training episodes.

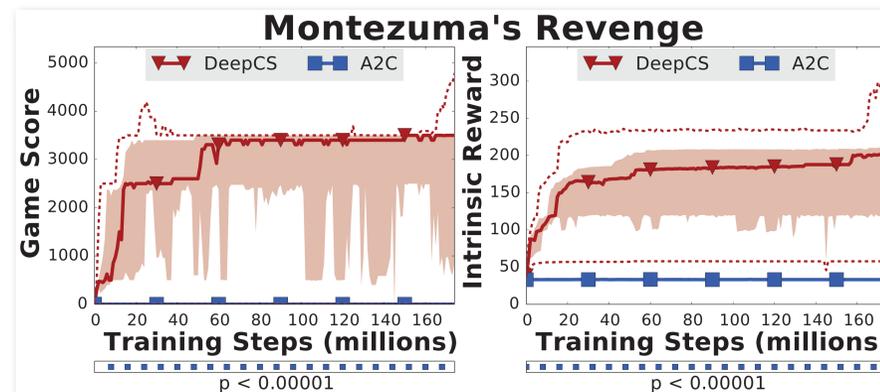
## Methods

- Game world is discretized into a uniform grid using RAM.
- Agent receives grid as extra input, as in previous work.<sup>1</sup>
- Intrinsic rewards are given for touching new grid tiles.

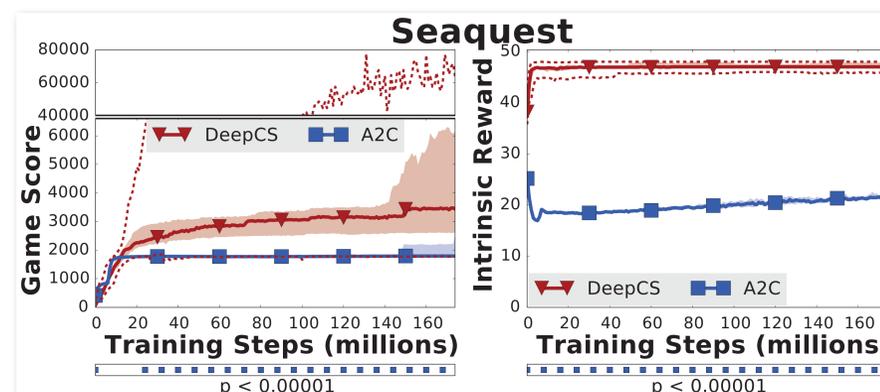


## Results

Naïve exploration algorithms usually achieve no score at all on Montezuma’s Revenge (MR), while Deep Curiosity Search (DeepCS) matches the performance of other state-of-the-art methods:



DeepCS also improves performance on some games in which directed exploration is seemingly not required, like Seaquest:

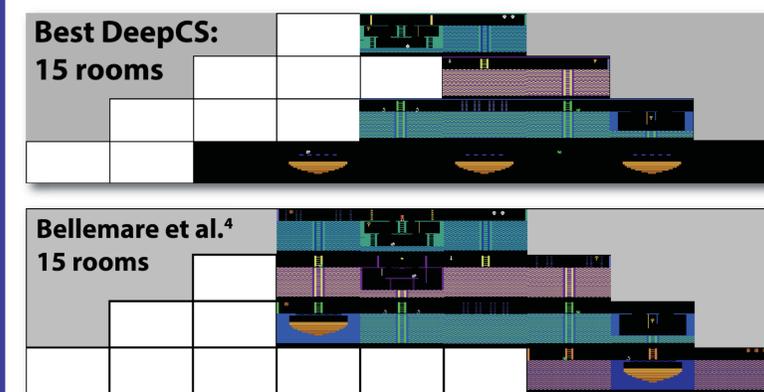


On 5 games, Deep Curiosity Search performs similarly or better than popular naïve- and directed-exploration algorithms:

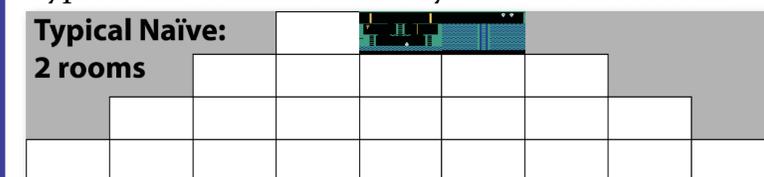
	DQN <sup>2</sup>	A3C <sup>3</sup>	PC <sup>4</sup>	PCn <sup>5</sup>	DeepCS
Amidar	739	283	964	900	<b>1404</b>
Freeway	30	0	30	31	<b>33</b>
Gravitar	306	269	246	859	<b>881</b>
MR	0	53	3439	<b>3705</b>	3500
Tutankham	186	156	132	190	<b>256</b>
Alien	<b>3069</b>	518	1945	1700	2705
Kangaroo	6740	94	5475	<b>7900</b>	2837
Pitfall	-	-78	-155	<b>0</b>	-186
Private Eye	1788	206	246	<b>15806</b>	1105
Seaquest	<b>5286</b>	2300	2274	2500	3443
Venture	380	23	0	<b>1356</b>	12
Wizard of Wor	3393	<b>17244</b>	3657	2500	2134

## Exploration

The best Deep Curiosity Search agent explores 15 rooms of Montezuma’s Revenge, matching other state-of-the-art exploration methods:



Typical naïve methods rarely exit the first room:



Even when the curiosity grid fills up quickly, the brief-lived intrinsic rewards can boost exploration:



Frame 0 (start): the grid has not yet been explored; DeepCS can provide lots of feedback  
 Frame 700: intrinsic rewards decline; DeepCS can no longer provide feedback  
 Frame 28,500: even brief presence of intrinsic rewards allows single agents to get 76,000 points

## Conclusions

- Encouraging intra-life novelty is an interesting new technique for improving exploration, in both sparse- and dense-reward domains.
- Providing agents with a visual memory of where they have been may help improve exploration.
- More general determination of agent position (e.g. by rewarding novelty in the latent space of an auto-encoder) may help Deep Curiosity Search become a general, even more useful tool.

[1] C. Stanton and J. Clune, “Curiosity Search: Producing generalists by encouraging individuals to continually explore and acquire skills throughout their lifetime,” *PLoS ONE*, 11(9): e0162235.  
 [2] Mnih et al., “Human-level control through deep reinforcement learning,” *Nature*, vol. 518, pp. 529-533, 2015.  
 [3] Mnih et al., “Asynchronous methods for deep reinforcement learning,” in *Proceedings of the 33rd International Conference on Machine Learning*, vol. 48, pp. 1928-1937, 2016.  
 [4] Bellemare et al., “Unifying count-based exploration and intrinsic motivation,” *30th Conference on Neural Information Processing Systems*, 2016.  
 [5] Ostrovski et al., “Count-based exploration with neural density models,” in *Proceedings of the 34th International Conference on Machine Learning*, vol. 70, pp. 2721-2730, 2017.